

# *Human-Enabled Science*



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## *Overview*



- Humans may accomplish many field scientific investigations better, faster and cheaper (science product/cost) than robots alone.
- Humans must be aided by robots because of environmental constraints; robots have increased performance if humans can be nearby
- Humans and robots working together will be required to expand scientific horizons through the creation of infrastructure



## *Background*

- Apollo Lunar Exploration
  - Demonstration of capability for field observations using simple tools
  - Complex sample collection – cores, rake, hammer
  - Documentation of samples
  - Demonstration of ability to work in the lunar environment
  - Identification of issues that restrict human explorers
- Hubble Space Telescope Repair
  - Complex manipulations allowed enhancement of instrument performance and extended lifetime

## *Robots vs. Humans as Field Geologists*

- Mars Athena Rover – Mars 2007 mission
  - ~200 kg instrumented rover
  - Capable of traversing several kilometers in 180 day mission, making detailed panoramas and crudely analyzing a few samples at three locations
- Apollo Astronaut
  - ~200 kg astronaut and suit
  - Capable of traversing several kilometers in 1 day, making in-situ observations and taking pictures, collecting several kilograms of sample for analysis
- In a variety of comparisons, humans on-site can perform approximately 2 orders of magnitude more rapidly and with better capability than automated rovers, for similar mass delivered to the surface



## *Robot-Aided Astronauts*

- Astronauts are limited in several ways
  - Must avoid hazardous terrain
  - Eyes are not as sensitive as spectrometers
  - Humans tire
- Robots can fill the gaps
  - Robotic field geologists may be expendable (?)
  - Field and laboratory instruments are extensions of human senses
  - Humans can teleoperate rovers without physically tiring; in some cases one human can operate several robots; or robots can be operated from afar

## *Unique Capabilities of Humans*

- Rapid decision-making based on synoptic observations
- Hand-eye coordination
- Abstract thought and communications
- Short term memory aids multitasking and synoptic observations
- Capability to improvise using tools and materials from the environment
- Subject for human life science investigations



### *An example: Determining the age of a rock*

- Rock age determinations require sample preparation and sophisticated mass spectrometric analysis.
- Absolute age determinations of rocks can be critical to understanding the sequence of geological/ biological events
- Typically, isotope chronology requires two separate rock components to be analyzed (eg a phase rich in a radioactive element and one poor in the same element, to serve as a background comparison)
- Concentrates must be separated from rocks containing the required minerals. This can be accomplished on Earth if a knowledgeable scientist has access to sample manipulation capabilities (eg magnetic separation, density separation). However, the conditions of separation vary from rock to rock. Therefore, the separation technique is quite iterative.

### *An example: Determining the age of a rock*

- Once separated, the mineral concentrates are subjected to chemical digestion and processing. This typically requires additional sample manipulation.
- The residue from sample processing must be converted to a form that is compatible with the mass spectrometer, including loading the sample onto the filament of an ion source.
- Once these have been done, mass spectrometry is straight forward and is typically carried out almost entirely by automated systems.
- The bottom line: Absolute chronology of Martian rocks will be done either in laboratories on Earth or laboratories on Mars



## *Human-Robotic Construction*

- Capabilities of robots
  - Repetitive tasks done without tiring
  - May be stronger than humans where required
  - May be more precise than humans where required
- Capabilities of humans
  - Respond rapidly to contingencies
  - Can cope with variable environment
  - Synoptic inspection both before and after assembly operation (is it going to fit? did it fit?)
  - Hand-eye coordination
  - Improvisation of tools
- Disadvantages of humans
  - Sometimes humans are clumsy
  - Sometimes humans make poor decisions under stress
  - Require infrastructure (life support systems, etc.)
  - Potential source of contamination

## *Humans, Plants and Animals*

- Expansion of humans beyond LEO is an important goal of space exploration.
- This will require understanding humans, plants and animals (food) in relevant environments
- Advantages of humans
  - Capable of working in environment that is poorly defined (plants do not always grow the same)
  - Synoptic observation (is a plant problem due to nutrition or insects?)
  - Effectively select and prepare appropriate samples for analysis



## *A Strategy for Improving Human Exploration Capabilities*

- Develop tools that augment human senses
  - Spectrometers, etc.
- Provide tools to augment human strength and diminish fatigue
  - Hand tools, better space suits
- Develop systems that optimize the time needed by humans to do tasks
  - Supervised robotic autonomy, teleoperation
- Develop infrastructure systems that make the environment more transparent to humans
  - Better space suits, space resource development, closed life support systems
- Improve human data integration and communication capabilities
  - Systems to improve team approach to exploration